

Complete Solutions to Miscellaneous Exercises 4

1. The given statement is false:

'Every linearly independent set in \mathbb{R}^n is an orthogonal set'.

Consider two linearly independent vectors such as $\mathbf{u} = \begin{pmatrix} 1 \\ 2 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ and $\mathbf{v} = \begin{pmatrix} 2 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ in \mathbb{R}^n .

These vectors are linearly independent but the inner (dot) product is

$$\mathbf{u} \cdot \mathbf{v} = 2 + 2 = 4$$

Hence \mathbf{u} and \mathbf{v} are not orthogonal so the given statement is false.

2. How do find an orthogonal basis for U from

$$\mathbf{X}_1 = [1, 1, 1, 1], \mathbf{X}_2 = [1, 0, 0, 1], \mathbf{X}_3 = [0, 2, 1, -1]?$$

Use the Gram Schmidt Process (4-10) which is given by

$$\text{Let } \mathbf{w}_1 = \mathbf{X}_1, \mathbf{w}_2 = \mathbf{X}_2 - \frac{\langle \mathbf{X}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \text{ and } \mathbf{w}_3 = \mathbf{X}_3 - \frac{\langle \mathbf{X}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{X}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2:$$

$$\text{Applying these we have } \mathbf{w}_1 = \mathbf{X}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}.$$

Evaluating each component of $\mathbf{w}_2 = \mathbf{X}_2 - \frac{\langle \mathbf{X}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$ gives:

$$\langle \mathbf{X}_2, \mathbf{w}_1 \rangle = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = 1 + 0 + 0 + 1 = 2 \text{ and } \|\mathbf{w}_1\|^2 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = 1^2 + 1^2 + 1^2 + 1^2 = 4$$

Substituting these $\mathbf{X}_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$, $\mathbf{w}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$, $\langle \mathbf{X}_2, \mathbf{w}_1 \rangle = 2$ and $\|\mathbf{w}_1\|^2 = 4$ into

$$\mathbf{w}_2 = \mathbf{X}_2 - \frac{\langle \mathbf{X}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \text{ gives}$$

$$\mathbf{w}_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} - \frac{2}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1-1/2 \\ 0-1/2 \\ 0-1/2 \\ 1-1/2 \end{bmatrix} = \begin{bmatrix} 1/2 \\ -1/2 \\ -1/2 \\ 1/2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix}$$

Remember we can ignore the fraction $1/2$ and find \mathbf{w}_3 that is orthogonal to

$$\mathbf{w}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \text{ and } \mathbf{w}'_2 = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} \quad [\mathbf{w}'_2 \text{ is } 2\mathbf{w}_2 \text{ that is we ignore } 1/2]$$

Determining each component of $\mathbf{w}_3 = \mathbf{X}_3 - \frac{\langle \mathbf{X}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{X}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$ gives

$$\langle \mathbf{X}_3, \mathbf{w}_1 \rangle = \mathbf{X}_3 \cdot \mathbf{w}_1 = \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = 0 + 2 + 1 - 1 = 2$$

$$\langle \mathbf{X}_3, \mathbf{w}'_2 \rangle = \mathbf{X}_3 \cdot \mathbf{w}'_2 = \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} = 0 + [2 \times (-1)] + [1 \times (-1)] + [-1 \times 1] = -4$$

$$\|\mathbf{w}'_2\|^2 = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} = 1^2 + (-1)^2 + (-1)^2 + 1^2 = 4$$

Substituting these, $\mathbf{X}_3 = \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \end{bmatrix}$, $\mathbf{w}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{w}'_2 = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix}$, $\langle \mathbf{X}_3, \mathbf{w}_1 \rangle = 2$, $\langle \mathbf{X}_3, \mathbf{w}'_2 \rangle = -4$,

$\|\mathbf{w}_1\|^2 = 4$ and $\|\mathbf{w}'_2\|^2 = 4$, into $\mathbf{w}_3 = \mathbf{X}_3 - \frac{\langle \mathbf{X}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{X}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$ yields

$$\begin{aligned} \mathbf{w}_3 &= \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \end{bmatrix} - \frac{2}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{-4}{4} \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 - 1/2 + 1 \\ 2 - 1/2 - 1 \\ 1 - 1/2 - 1 \\ -1 - 1/2 + 1 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 1/2 \\ -1/2 \\ -1/2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} \end{aligned}$$

Again we can remove the fraction and let $\mathbf{w}'_3 = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$. Thus our orthogonal vectors are

$$\mathbf{w}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{w}'_2 = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} \quad \text{and} \quad \mathbf{w}'_3 = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} \quad \text{which means that } \{\mathbf{w}_1, \mathbf{w}'_2, \mathbf{w}'_3\} \text{ forms an}$$

orthogonal set of vectors which is a orthogonal basis for U .

3. (a) We are given that $S = \text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix} \right\}$ and if these vectors are linearly

independent then they form a basis for S .

Let k_1, k_2 and k_3 be scalars such that

$$k_1 \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + k_2 \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} + k_3 \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

For the given vectors to be linearly independent we need to prove that $k_1 = k_2 = k_3 = 0$.

Writing the above as equations we have

$$k_1 + k_3 = 0 \quad (1)$$

$$k_2 + k_3 = 0 \quad (2)$$

$$k_1 + k_2 + 2k_3 = 0 \quad (3)$$

$$k_2 + 2k_3 = 0 \quad (4)$$

From equations (2) and (3) we have $k_2 = k_3 = 0$. Substituting this into equation (3)

gives $k_1 = 0$. Hence the given vectors are linearly independent because $k_1 = k_2 = k_3 = 0$ therefore they form a basis for S . [Remember they already span the space S].

(b) We need to apply the Gram Schmidt Process (4-10) which is:

$$\mathbf{w}_1 = \mathbf{v}_1, \quad \mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \quad \text{and} \quad \mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

$$\text{Let } \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad \text{and} \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix} \quad \text{which are the given vectors.}$$

By using (4-10) we have $\mathbf{w}_1 = \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$. For $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$ so we need to find

$\langle \mathbf{v}_2, \mathbf{w}_1 \rangle$ and $\|\mathbf{w}_1\|^2$:

$$\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = \mathbf{v}_2 \cdot \mathbf{w}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = 0 + 0 + 1 + 0 = 1$$

$$\|\mathbf{w}_1\|^2 = \mathbf{w}_1 \cdot \mathbf{w}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = 1 + 0 + 1 + 0 = 2$$

Putting $\mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{w}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$, $\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = 1$ and $\|\mathbf{w}_1\|^2 = 2$ into $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\mathbf{w}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 - 1/2 \\ 1 - 0 \\ 1 - 1/2 \\ 1 - 0 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 1 \\ 1/2 \\ 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -1 \\ 2 \\ 1 \\ 2 \end{bmatrix}$$

Remove the fraction so that the arithmetic for evaluating \mathbf{w}_3 is easier, that is let

$$\mathbf{w}'_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \\ 2 \end{bmatrix}$$

How do we determine \mathbf{w}_3 ?

By using the above (4-10), that is $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$:

$$\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = 1 + 0 + 2 + 0 = 3$$

$$\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 2 \\ 1 \\ 2 \end{bmatrix} = [1 \times (-1)] + [1 \times 2] + [2 \times 1] + [2 \times 2] = 7$$

$$\|\mathbf{w}'_2\|^2 = \begin{bmatrix} -1 \\ 2 \\ 1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 2 \\ 1 \\ 2 \end{bmatrix} = (-1)^2 + 2^2 + 1^2 + 2^2 = 10$$

$$\text{Substituting } \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix}, \mathbf{w}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \mathbf{w}'_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \\ 2 \end{bmatrix}, \langle \mathbf{v}_3, \mathbf{w}_1 \rangle = 3, \langle \mathbf{v}_3, \mathbf{w}'_2 \rangle = 7, \|\mathbf{w}_1\|^2 = 2$$

and $\|\mathbf{w}'_2\|^2 = 10$ into $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$ gives

$$\begin{aligned} \mathbf{w}_3 &= \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix} - \frac{3}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} - \frac{7}{10} \begin{bmatrix} -1 \\ 2 \\ 1 \\ 2 \end{bmatrix} \\ &= \begin{bmatrix} 1-3/2+7/10 \\ 1-0-14/10 \\ 2-3/2-7/10 \\ 2-0-14/10 \end{bmatrix} = \begin{bmatrix} 1/5 \\ -2/5 \\ -1/5 \\ 3/5 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 1 \\ -2 \\ -1 \\ 3 \end{bmatrix} \end{aligned}$$

Again we can ignore the fraction to simplify our calculations, that is let

$$\mathbf{w}'_3 = \begin{bmatrix} 1 \\ -2 \\ -1 \\ 3 \end{bmatrix}$$

Our orthogonal basis is $\{\mathbf{w}_1, \mathbf{w}'_2, \mathbf{w}'_3\}$. *How do we convert these into orthonormal basis?*

By normalising each of these vectors:

$$\mathbf{w}_1 = \frac{1}{\|\mathbf{w}_1\|} \mathbf{w}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \mathbf{w}'_2 = \frac{1}{\|\mathbf{w}'_2\|} \mathbf{w}'_2 = \frac{1}{\sqrt{10}} \begin{bmatrix} -1 \\ 2 \\ 1 \\ 2 \end{bmatrix} \text{ and } \mathbf{w}'_3 = \frac{1}{\|\mathbf{w}'_3\|} \mathbf{w}'_3 = \frac{1}{\sqrt{15}} \begin{bmatrix} 1 \\ -2 \\ -1 \\ 3 \end{bmatrix}$$

Hence our orthonormal basis for S is $\{\mathbf{w}_1, \mathbf{w}'_2, \mathbf{w}'_3\}$.

4. (a) Let $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ be a basis of a Euclidean space V . This basis is orthogonal if each of the vectors in the basis are orthogonal to each other, that is

$$\langle \mathbf{v}_i, \mathbf{v}_j \rangle = 0 \text{ where } i \neq j$$

This basis is orthonormal if we also have

$$\|\mathbf{v}_j\| = 1 \text{ for all } j = 1, 2, \dots, n$$

(b) To show that the given vectors $\mathbf{f}_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}$, $\mathbf{f}_2 = \begin{pmatrix} 0 \\ -2 \\ 3 \end{pmatrix}$ and $\mathbf{f}_3 = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix}$ form a basis of

\mathbb{R}^3 it is enough to show that they are linearly independent.

Let k_1 , k_2 and k_3 be scalars such that

$$k_1 \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} + k_2 \begin{pmatrix} 0 \\ -2 \\ 3 \end{pmatrix} + k_3 \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Writing these out as equations we have

$$-k_1 + k_3 = 0 \quad (1)$$

$$-2k_2 + k_3 = 0 \quad (2)$$

$$2k_1 + 3k_2 + 4k_3 = 0 \quad (3)$$

From equation (1) we have $k_3 = k_1$ and equation (2) we have $k_3 = 2k_2$ implies $k_1 = 2k_2$.

Substituting $k_1 = 2k_2$ and $k_3 = 2k_2$ into the bottom equation:

$$2(2k_2) + 3k_2 + 4(2k_2) = 15k_2 = 0 \text{ gives } k_2 = 0$$

Substituting $k_2 = 0$ into $k_1 = 2k_2$ and $k_3 = 2k_2$ gives $k_1 = 0$ and $k_3 = 0$.

Thus the given vectors $\mathbf{f}_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}$, $\mathbf{f}_2 = \begin{pmatrix} 0 \\ -2 \\ 3 \end{pmatrix}$ and $\mathbf{f}_3 = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix}$ are linearly independent so

they form a basis for \mathbb{R}^3 because by question 12 of Exercises 3.5 which says:

n linearly independent vectors in \mathbb{R}^n form a basis for \mathbb{R}^n .

We only need three linearly independent vectors.

(c) We need to apply the Gram Schmidt Process (4-10) which is:

$$\mathbf{w}_1 = \mathbf{v}_1, \mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \text{ and } \mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

By replacing \mathbf{v} with \mathbf{f} in the above we have $\mathbf{w}_1 = \mathbf{f}_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}$ and $\mathbf{w}_2 = \mathbf{f}_2 - \frac{\langle \mathbf{f}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\langle \mathbf{f}_2, \mathbf{w}_1 \rangle = \mathbf{f}_2 \cdot \mathbf{w}_1 = \begin{pmatrix} 0 \\ -2 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} = 0 + 0 + 6 = 6$$

$$\|\mathbf{w}_1\|^2 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} = (-1)^2 + 0^2 + 2^2 = 5$$

Putting $\mathbf{w}_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}$, $\mathbf{f}_2 = \begin{pmatrix} 0 \\ -2 \\ 3 \end{pmatrix}$, $\langle \mathbf{f}_2, \mathbf{w}_1 \rangle = 6$ and $\|\mathbf{w}_1\|^2 = 5$ into $\mathbf{w}_2 = \mathbf{f}_2 - \frac{\langle \mathbf{f}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\begin{aligned}\mathbf{w}_2 &= \begin{pmatrix} 0 \\ -2 \\ 3 \end{pmatrix} - \frac{6}{5} \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} \\ &= \begin{pmatrix} 0+6/5 \\ -2-0 \\ 3-12/5 \end{pmatrix} = \begin{pmatrix} 6/5 \\ -2 \\ 3/5 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 6 \\ -10 \\ 3 \end{pmatrix}\end{aligned}$$

We can ignore the fraction and write this as

$$\mathbf{w}'_2 = \begin{pmatrix} 6 \\ -10 \\ 3 \end{pmatrix}$$

What else do we need to find?

\mathbf{w}_3 which is given by $\mathbf{w}_3 = \mathbf{f}_3 - \frac{\langle \mathbf{f}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{f}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$. Finding each component:

$$\langle \mathbf{f}_3, \mathbf{w}_1 \rangle = \mathbf{f}_3 \cdot \mathbf{w}_1 = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} = -1 + 0 + 8 = 7$$

$$\langle \mathbf{f}_3, \mathbf{w}'_2 \rangle = \mathbf{f}_3 \cdot \mathbf{w}'_2 = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 6 \\ -10 \\ 3 \end{pmatrix} = 6 - 10 + 12 = 8$$

$$\|\mathbf{w}'_2\|^2 = \mathbf{w}'_2 \cdot \mathbf{w}'_2 = \begin{pmatrix} 6 \\ -10 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 6 \\ -10 \\ 3 \end{pmatrix} = 6^2 + (-10)^2 + 3^2 = 145$$

Substituting $\mathbf{f}_3 = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix}$, $\mathbf{w}_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}$, $\mathbf{w}'_2 = \begin{pmatrix} 6 \\ -10 \\ 3 \end{pmatrix}$, $\langle \mathbf{f}_3, \mathbf{w}_1 \rangle = 7$, $\langle \mathbf{f}_3, \mathbf{w}'_2 \rangle = 8$,

$\|\mathbf{w}'_2\|^2 = 145$ and $\|\mathbf{w}_1\|^2 = 5$ into $\mathbf{w}_3 = \mathbf{f}_3 - \frac{\langle \mathbf{f}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{f}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$ gives

$$\begin{aligned}\mathbf{w}_3 &= \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix} - \frac{7}{5} \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} - \frac{8}{145} \begin{pmatrix} 6 \\ -10 \\ 3 \end{pmatrix} \\ &= \begin{pmatrix} 1+7/5-48/145 \\ 1-0+80/145 \\ 4-14/5-24/145 \end{pmatrix} = \begin{pmatrix} 60/29 \\ 45/29 \\ 30/29 \end{pmatrix} = \frac{15}{29} \begin{pmatrix} 4 \\ 3 \\ 2 \end{pmatrix}\end{aligned}$$

Again ignore the fraction and let $\mathbf{w}'_3 = \begin{pmatrix} 4 \\ 3 \\ 2 \end{pmatrix}$.

Hence our orthogonal basis is $\left\{ \mathbf{w}_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}, \mathbf{w}'_2 = \begin{pmatrix} 6 \\ -10 \\ 3 \end{pmatrix}, \mathbf{w}'_3 = \begin{pmatrix} 4 \\ 3 \\ 2 \end{pmatrix} \right\}$.

5. (a) We need to prove that an orthogonal set of non-zero vectors in \mathbb{R}^n are linearly independent.

Proof.

Let $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\}$ be an orthogonal set of non-zero vectors in \mathbb{R}^n and k_1, k_2, \dots, k_m be scalars such that

$$k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_m \mathbf{v}_m = \mathbf{0} \quad (*)$$

What do we need to prove?

Need to show that $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\}$ is linearly independent which means prove that $k_1 = k_2 = \dots = k_m = 0$.

Consider the inner product $\langle \mathbf{v}_1, \mathbf{0} \rangle = 0$. Substituting (*) for the zero vector into this gives

$$\begin{aligned} \langle \mathbf{v}_1, \mathbf{0} \rangle &= \langle \mathbf{v}_1, k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_m \mathbf{v}_m \rangle \\ &= k_1 \langle \mathbf{v}_1, \mathbf{v}_1 \rangle + k_2 \langle \mathbf{v}_1, \mathbf{v}_2 \rangle + \dots + k_m \langle \mathbf{v}_1, \mathbf{v}_m \rangle \\ &= k_1 \|\mathbf{v}_1\|^2 + k_2 (0) + \dots + k_m (0) \quad [\text{Since } \mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m \text{ are orthogonal}] \\ &= k_1 \|\mathbf{v}_1\|^2 \end{aligned}$$

We have $k_1 \|\mathbf{v}_1\|^2 = 0$ but $\mathbf{v}_1 \neq \mathbf{0}$ [Not Zero] therefore $k_1 = 0$.

By expanding $\langle \mathbf{v}_2, \mathbf{0} \rangle = \langle \mathbf{v}_3, \mathbf{0} \rangle = \dots = \langle \mathbf{v}_n, \mathbf{0} \rangle = 0$ and repeating the above argument we have $k_2 = k_3 = \dots = k_m = 0$. Thus we have $k_1 = k_2 = \dots = k_m = 0$ which means that $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\}$ is linearly independent. ■

(b) We need to prove that

$$\mathbf{w} = (\mathbf{v}_1 \cdot \mathbf{w}) \mathbf{v}_1 + (\mathbf{v}_2 \cdot \mathbf{w}) \mathbf{v}_2 + \dots + (\mathbf{v}_n \cdot \mathbf{w}) \mathbf{v}_n$$

Proof.

We are given that $B = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ is an orthonormal basis of \mathbb{R}^n . There exists scalars k_1, k_2, \dots, k_n such that

$$\mathbf{w} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_n \mathbf{v}_n$$

Required to prove that $k_1 = (\mathbf{v}_1 \cdot \mathbf{w})$, $k_2 = (\mathbf{v}_2 \cdot \mathbf{w})$, \dots , $k_n = (\mathbf{v}_n \cdot \mathbf{w})$. Consider the inner product of the vector \mathbf{v}_j (where j is any integer from 1 to n) and \mathbf{w} :

$$\begin{aligned} \mathbf{v}_j \cdot \mathbf{w} &= \mathbf{v}_j \cdot (k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_n \mathbf{v}_n) \quad [\text{Because } \mathbf{w} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_n \mathbf{v}_n] \\ &= k_1 (\mathbf{v}_j \cdot \mathbf{v}_1) + k_2 (\mathbf{v}_j \cdot \mathbf{v}_2) + \dots + k_j (\mathbf{v}_j \cdot \mathbf{v}_j) + \dots + k_n (\mathbf{v}_j \cdot \mathbf{v}_n) \\ &= k_1 (0) + k_2 (0) + \dots + k_j \|\mathbf{v}_j\|^2 + \dots + k_n (0) \quad \left[\begin{array}{l} \text{Because } \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \\ \text{is orthonormal} \end{array} \right] \\ &= k_j \|\mathbf{v}_j\|^2 = k_j \quad [\text{Because } \mathbf{v}_j \text{ is orthonormal, normalised vector}] \end{aligned}$$

Hence we have $k_j = \mathbf{v}_j \cdot \mathbf{w}$. Since j was an arbitrary integer between 1 and n therefore the result is true for any j , that is $k_1 = (\mathbf{v}_1 \cdot \mathbf{w})$, $k_2 = (\mathbf{v}_2 \cdot \mathbf{w})$, \dots , $k_n = (\mathbf{v}_n \cdot \mathbf{w})$. This completes our proof. ■

6. (a) The vectors $\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3$ in \mathbb{R}^3 are orthonormal means that **both** the following conditions are satisfied:

$$\langle \mathbf{w}_1, \mathbf{w}_2 \rangle = \langle \mathbf{w}_1, \mathbf{w}_3 \rangle = \langle \mathbf{w}_2, \mathbf{w}_3 \rangle = 0 \text{ and}$$

$$\|\mathbf{w}_1\| = \|\mathbf{w}_2\| = \|\mathbf{w}_3\| = 1$$

(b) We need to convert $\mathbf{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{v}_3 = \begin{bmatrix} 5 \\ 4 \\ 6 \end{bmatrix}$ into an orthonormal set by

applying the Gram Schmidt Process (4-10) which is

$$\mathbf{w}_1 = \mathbf{v}_1, \mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \text{ and } \mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

We have $\mathbf{w}_1 = \mathbf{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$. We need to evaluate $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = \mathbf{v}_2 \cdot \mathbf{w}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = 0 + 1 + 0 = 1$$

$$\|\mathbf{w}_1\|^2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = 0^2 + 1^2 + 1^2 = 2$$

Substituting $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{w}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$, $\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = 1$, $\|\mathbf{w}_1\|^2 = 2$ into $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$

gives

$$\begin{aligned} \mathbf{w}_2 &= \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 1-0 \\ 1-1/2 \\ 0-1/2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1/2 \\ -1/2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} \end{aligned}$$

Ignore the fraction so that evaluating \mathbf{w}_3 is made easier, that is let

$$\mathbf{w}'_2 = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$$

What else do we need to find?

The vector \mathbf{w}_3 which is given by $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$:

$$\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = \mathbf{v}_3 \cdot \mathbf{w}_1 = \begin{bmatrix} 5 \\ 4 \\ 6 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = (5 \times 0) + (4 \times 1) + (6 \times 1) = 10$$

$$\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle = \mathbf{v}_3 \cdot \mathbf{w}'_2 = \begin{bmatrix} 5 \\ 4 \\ 6 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = (5 \times 2) + (4 \times 1) + (6 \times (-1)) = 8$$

$$\|\mathbf{w}'_2\|^2 = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = 2^2 + 1^2 + (-1)^2 = 6$$

Substituting $\mathbf{v}_3 = \begin{bmatrix} 5 \\ 4 \\ 6 \end{bmatrix}$, $\mathbf{w}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{w}'_2 = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$, $\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = 10$, $\|\mathbf{w}_1\|^2 = 2$,

$\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle = 8$ and $\|\mathbf{w}'_2\|^2 = 6$ into $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$ gives

$$\begin{aligned} \mathbf{w}_3 &= \begin{bmatrix} 5 \\ 4 \\ 6 \end{bmatrix} - \frac{10}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{8}{6} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} \\ &= \begin{bmatrix} 5 \\ 4 \\ 6 \end{bmatrix} - 5 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{4}{3} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 5-0-8/3 \\ 4-5-4/3 \\ 6-5+4/3 \end{bmatrix} = \begin{bmatrix} 7/3 \\ -7/3 \\ 7/3 \end{bmatrix} = \frac{7}{3} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \end{aligned}$$

Again ignore the fraction and let $\mathbf{w}'_3 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$.

Hence our orthogonal vectors in \square^3 are $\mathbf{w}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{w}'_2 = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$ and $\mathbf{w}'_3 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$.

We need to normalise these vectors so that we have an orthonormal set:

$$\mathbf{w}_1 = \frac{1}{\|\mathbf{w}_1\|} \mathbf{w}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{w}'_2 = \frac{1}{\|\mathbf{w}'_2\|} \mathbf{w}'_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} \text{ and } \mathbf{w}'_3 = \frac{1}{\|\mathbf{w}'_3\|} \mathbf{w}'_3 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

Hence our orthonormal set in \square^3 is $\left\{ \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}, \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\}$.

7. (a) The norm $\|\mathbf{x}\|$ of $\mathbf{x} = (x_1, x_2, x_3, x_4)$ is defined as

$$\begin{aligned}\|\mathbf{x}\| &= \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle} \\ &= \sqrt{\mathbf{x} \cdot \mathbf{x}} = \sqrt{x_1^2 + x_2^2 + x_3^2 + x_4^2}\end{aligned}$$

We have

$$\|(2, -3, 5, 1)\| = \sqrt{2^2 + (-3)^2 + 5^2 + 1^2} = \sqrt{39}$$

(b) We say two vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^4$ are orthogonal if

$$\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x} \cdot \mathbf{y} = 0$$

Checking the given vectors:

$$\langle (0, 1, -1, 1), (6, 3, 3, 27) \rangle = (0 \times 6) + (1 \times 3) + (-1 \times 3) + (1 \times 27) = 27$$

Since $\langle (0, 1, -1, 1), (6, 3, 3, 27) \rangle = 27 \neq 0$ therefore the given vectors are **not** orthogonal.

(c) An orthonormal set of vectors in \mathbb{R}^4 is a set of vectors where each vector is orthogonal to each other and every vector has a norm of 1.

Checking Orthogonality:

$$\left\langle (0, 0, 1, 0), \left(\frac{1}{\sqrt{6}}, \frac{-2}{\sqrt{6}}, 0, \frac{1}{\sqrt{6}} \right) \right\rangle = 0 + 0 + 0 + 0 = 0$$

$$\left\langle (0, 0, 1, 0), \left(\frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0, 0 \right) \right\rangle = 0$$

$$\left\langle \left(\frac{1}{\sqrt{6}}, \frac{-2}{\sqrt{6}}, 0, \frac{1}{\sqrt{6}} \right), \left(\frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0, 0 \right) \right\rangle = \frac{2}{\sqrt{30}} - \frac{2}{\sqrt{30}} + 0 + 0 = 0$$

Hence the given vectors are orthogonal.

Checking Normality:

$$\|(0, 0, 1, 0)\| = 1$$

$$\left\| \left(\frac{1}{\sqrt{6}}, \frac{-2}{\sqrt{6}}, 0, \frac{1}{\sqrt{6}} \right) \right\| = \frac{1}{6} + \frac{4}{6} + 0 + \frac{1}{6} = 1$$

$$\left\| \left(\frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0, 0 \right) \right\| = \frac{4}{5} + \frac{1}{5} + 0 + 0 = 1$$

Each vector has a norm of 1.

Since all three of the given vectors are orthogonal and each has a norm of 1 therefore

$\left\{ (0, 0, 1, 0), \left(\frac{1}{\sqrt{6}}, \frac{-2}{\sqrt{6}}, 0, \frac{1}{\sqrt{6}} \right), \left(\frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0, 0 \right) \right\}$ is an orthonormal

set.

(d) The Gram-Schmidt process (4-10) is given by

$$\text{Let } \mathbf{w}_1 = \mathbf{v}_1, \mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$$

$$\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

$$\mathbf{w}_4 = \mathbf{v}_4 - \frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2 - \frac{\langle \mathbf{v}_4, \mathbf{w}_3 \rangle}{\|\mathbf{w}_3\|^2} \mathbf{w}_3$$

$$\vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots$$

Applying this to the given vectors:

$$\mathbf{v}_1 = (1, 0, 0, 0), \mathbf{v}_2 = (1, 1, 0, 1), \mathbf{v}_3 = (0, 1, 1, 1), \mathbf{v}_4 = (0, 1, -1, 0)$$

we have $\mathbf{w}_1 = \mathbf{v}_1 = (1, 0, 0, 0)$. We need to find $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$.

Evaluating each component of this we have

$$\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = \mathbf{v}_2 \cdot \mathbf{w}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = 1 + 0 + 0 + 0 = 1$$

$$\|\mathbf{w}_1\|^2 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = 1$$

Putting $\mathbf{v}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 1 \end{pmatrix}$, $\mathbf{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$, $\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = 1$ and $\|\mathbf{w}_1\|^2 = 1$ into $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\mathbf{w}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 1 \end{pmatrix} - \frac{1}{1} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1-1 \\ 1-0 \\ 0-0 \\ 1-0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

Next we need to find $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$:

$$\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = \mathbf{v}_3 \cdot \mathbf{w}_1 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = 0$$

$$\langle \mathbf{v}_3, \mathbf{w}_2 \rangle = \mathbf{v}_3 \cdot \mathbf{w}_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} = 0 + 1 + 0 + 1 = 2$$

$$\|\mathbf{w}_2\|^2 = \mathbf{w}_2 \cdot \mathbf{w}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} = 0^2 + 1^2 + 0^2 + 1^2 = 2$$

Substituting $\mathbf{v}_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix}$, $\mathbf{w}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}$, $\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = 0$, $\langle \mathbf{v}_3, \mathbf{w}_2 \rangle = 2$ and $\|\mathbf{w}_2\|^2 = 2$ into

$\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$ gives:

$$\mathbf{w}_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} - 0\mathbf{w}_1 - \frac{2}{2} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0-0 \\ 1-1 \\ 1-0 \\ 1-1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

We need to find $\mathbf{w}_4 = \mathbf{v}_4 - \frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2 - \frac{\langle \mathbf{v}_4, \mathbf{w}_3 \rangle}{\|\mathbf{w}_3\|^2} \mathbf{w}_3$:

$$\langle \mathbf{v}_4, \mathbf{w}_1 \rangle = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = (0 \times 1) + (1 \times 0) + (-1 \times 0) + (0 \times 0) = 0$$

$$\langle \mathbf{v}_4, \mathbf{w}_2 \rangle = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} = (0 \times 0) + (1 \times 1) + (-1 \times 0) + (0 \times 1) = 1$$

$$\langle \mathbf{v}_4, \mathbf{w}_3 \rangle = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = (0 \times 0) + (1 \times 0) + (-1 \times 1) + (0 \times 0) = -1$$

$$\|\mathbf{w}_3\|^2 = \langle \mathbf{w}_3, \mathbf{w}_3 \rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = 0^2 + 0^2 + 1^2 + 0^2 = 1$$

Substituting $\mathbf{v}_4 = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix}$, $\mathbf{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$, $\mathbf{w}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}$, $\mathbf{w}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$, $\langle \mathbf{v}_4, \mathbf{w}_1 \rangle = 0$, $\|\mathbf{w}_1\|^2 = 1$,

$\langle \mathbf{v}_4, \mathbf{w}_2 \rangle = 1$, $\|\mathbf{w}_2\|^2 = 2$, $\langle \mathbf{v}_4, \mathbf{w}_3 \rangle = -1$ and $\|\mathbf{w}_3\|^2 = 1$ into

$\mathbf{w}_4 = \mathbf{v}_4 - \frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2 - \frac{\langle \mathbf{v}_4, \mathbf{w}_3 \rangle}{\|\mathbf{w}_3\|^2} \mathbf{w}_3$ gives

$$\mathbf{w}_4 = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} - 0\mathbf{w}_1 - \frac{1}{2} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} - \frac{-1}{1} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0-0+0 \\ 1-1/2+0 \\ -1-0+1 \\ 0-1/2+0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1/2 \\ 0 \\ -1/2 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

Ignore the fraction and let $\mathbf{w}'_4 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}$. We have our orthogonal set of vectors

$$\mathbf{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \mathbf{w}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}, \mathbf{w}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \text{ and } \mathbf{w}'_4 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

We need to normalise these vectors. Clearly \mathbf{w}_1 and \mathbf{w}_3 have a norm of 1 therefore we do **not** need to normalise these.

$$\mathbf{w}_2 = \frac{1}{\|\mathbf{w}_2\|} \mathbf{w}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

$$\mathbf{w}'_4 = \frac{1}{\|\mathbf{w}'_4\|} \mathbf{w}'_4 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

Hence our orthonormal basis is $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3, \mathbf{w}'_4\}$.

8. (a) Let $\mathbf{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. The norm $\|\mathbf{A}\|$ of $\mathbf{A} \in M(2, 2)$ is defined as

$$\|\mathbf{A}\| = \sqrt{\langle \mathbf{A}, \mathbf{A} \rangle} = \sqrt{\text{tr}(\mathbf{A}^T \mathbf{A})} \quad (*)$$

We have

$$\text{tr}(\mathbf{A}^T \mathbf{A}) = \text{tr} \left(\begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) \quad \left[\text{Because } \mathbf{A}^T = \begin{pmatrix} a & b \\ c & d \end{pmatrix}^T = \begin{pmatrix} a & c \\ b & d \end{pmatrix} \right]$$

$$= \text{tr} \begin{pmatrix} a^2 + c^2 & ab + cd \\ ab + cd & b^2 + d^2 \end{pmatrix}$$

$$= a^2 + b^2 + c^2 + d^2$$

[Because the trace is the addition of leading diagonal entries]

Substituting this $\text{tr}(\mathbf{A}^T \mathbf{A}) = a^2 + b^2 + c^2 + d^2$ into (*) gives

$$\|\mathbf{A}\| = \sqrt{a^2 + b^2 + c^2 + d^2} \quad (\odot)$$

For the given matrix we have

$$\left\| \begin{pmatrix} 2 & -3 \\ 5 & 1 \end{pmatrix} \right\| = \sqrt{2^2 + (-3)^2 + 5^2 + 1^2} = \sqrt{39}$$

(b) Matrices \mathbf{A} and \mathbf{B} are orthogonal if $\langle \mathbf{A}, \mathbf{B} \rangle = \text{tr}(\mathbf{B}^T \mathbf{A}) = 0$.

For the given matrices we have

$$\begin{aligned} \left\langle \begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix}, \begin{pmatrix} 6 & 3 \\ 3 & 27 \end{pmatrix} \right\rangle &= \text{tr} \left(\begin{pmatrix} 6 & 3 \\ 3 & 27 \end{pmatrix}^T \begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix} \right) \\ &= \text{tr} \left(\begin{pmatrix} 6 & 3 \\ 3 & 27 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix} \right) = \text{tr} \begin{pmatrix} -3 & 9 \\ -27 & 30 \end{pmatrix} = -3 + 30 = 27 \end{aligned}$$

Thus the given matrices are **not** orthogonal.

(c) Orthonormal set of matrices are a set of matrices which are orthogonal and have a norm of 1.

Checking Orthogonality: We need to find $\langle \mathbf{A}_2, \mathbf{A}_1 \rangle$, $\langle \mathbf{A}_3, \mathbf{A}_1 \rangle$, $\langle \mathbf{A}_3, \mathbf{A}_2 \rangle$:

$$\begin{aligned} \langle \mathbf{A}_2, \mathbf{A}_1 \rangle &= \text{tr} \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}^T \begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix} \right) \\ &= \text{tr} \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix} \right) = \text{tr} \begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 0 \end{pmatrix} = 0 + 0 = 0 \\ \langle \mathbf{A}_3, \mathbf{A}_1 \rangle &= \text{tr} \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}^T \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) \\ &= \text{tr} \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) = \text{tr} \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = 0 + 0 = 0 \\ \langle \mathbf{A}_3, \mathbf{A}_2 \rangle &= \text{tr} \left(\begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix}^T \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) \\ &= \text{tr} \left(\begin{pmatrix} 0 & 0 \\ 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) = \text{tr} \begin{pmatrix} 0 & 0 \\ 1/\sqrt{2} & 0 \end{pmatrix} = 0 + 0 = 0 \end{aligned}$$

Since $\langle \mathbf{A}_2, \mathbf{A}_1 \rangle = \langle \mathbf{A}_3, \mathbf{A}_1 \rangle = \langle \mathbf{A}_3, \mathbf{A}_2 \rangle = 0$ therefore the given set

$$\left\{ \mathbf{A}_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \mathbf{A}_2 = \begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix}, \mathbf{A}_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right\}$$

is an orthogonal set of matrices.

Checking Normality:

We also need to check that each of these have a norm of 1 to ensure they are orthonormal. *How?*

We can use (\odot) above which is

$$\|\mathbf{A}\| = \sqrt{a^2 + b^2 + c^2 + d^2} \quad \text{where } \mathbf{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$\|\mathbf{A}_1\| = \left\| \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right\| = \sqrt{1^2 + 0^2 + 0^2 + 0^2} = 1$$

$$\|\mathbf{A}_2\|^2 = \left\| \begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix} \right\|^2 = \sqrt{0^2 + \left(\frac{1}{\sqrt{2}}\right)^2 + 0^2 + \left(\frac{1}{\sqrt{2}}\right)^2} = 1$$

$$\|\mathbf{A}_3\|^2 = \left\| \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right\|^2 = \sqrt{0^2 + 0^2 + 1^2 + 0^2} = 1$$

Taking the square root of each we have $\|\mathbf{A}_1\| = \|\mathbf{A}_2\| = \|\mathbf{A}_3\| = 1$. Hence the given set of matrices are orthonormal.

(d) The first three matrices of the set $\{\mathbf{A}_1, \mathbf{A}_2, \mathbf{A}_3, \mathbf{A}_4\}$ are orthonormal as shown in part (c) above. We need to find a matrix \mathbf{A}_4 which is orthogonal to $\mathbf{A}_1, \mathbf{A}_2, \mathbf{A}_3$ and is of norm 1. *How do we find this \mathbf{A}_4 ?*

Use Gram-Schmidt Process (4-10) which is

$$\mathbf{w}_4 = \mathbf{v}_4 - \frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2 - \frac{\langle \mathbf{v}_4, \mathbf{w}_3 \rangle}{\|\mathbf{w}_3\|^2} \mathbf{w}_3 \quad (*)$$

Let $\mathbf{w}_1 = \mathbf{A}_1, \mathbf{w}_2 = \mathbf{A}_2, \mathbf{w}_3 = \mathbf{A}_3$ because these are already orthonormal which also means that $\|\mathbf{w}_1\|^2 = \|\mathbf{A}_1\|^2 = 1, \|\mathbf{w}_2\|^2 = \|\mathbf{A}_2\|^2 = 1$ and $\|\mathbf{w}_3\|^2 = \|\mathbf{A}_3\|^2 = 1$.

Let $\mathbf{v}_4 = \mathbf{B}$ and $\mathbf{w}_4 = \mathbf{A}_4$ so substituting $\mathbf{w}_1 = \mathbf{A}_1, \mathbf{w}_2 = \mathbf{A}_2, \mathbf{w}_3 = \mathbf{A}_3$ and $\|\mathbf{w}_1\|^2 = \|\mathbf{w}_2\|^2 = \|\mathbf{w}_3\|^2 = 1$ into (*) gives

$$\mathbf{A}_4 = \mathbf{B} - \langle \mathbf{B}, \mathbf{A}_1 \rangle \mathbf{A}_1 - \langle \mathbf{B}, \mathbf{A}_2 \rangle \mathbf{A}_2 - \langle \mathbf{B}, \mathbf{A}_3 \rangle \mathbf{A}_3 \quad (**)$$

Evaluating each component of (**):

$$\langle \mathbf{B}, \mathbf{A}_1 \rangle = \langle \mathbf{A}_1, \mathbf{B} \rangle = \text{tr} \left[\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^T \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right] = \text{tr} \left[\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right] = \text{tr} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = 0$$

$$\langle \mathbf{B}, \mathbf{A}_2 \rangle = \langle \mathbf{A}_2, \mathbf{B} \rangle = \text{tr} \left[\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix} \right] = \text{tr} \begin{pmatrix} 0 & -1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix} = \frac{1}{\sqrt{2}}$$

$$\langle \mathbf{B}, \mathbf{A}_3 \rangle = \langle \mathbf{A}_3, \mathbf{B} \rangle = \text{tr} \left[\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right] = \text{tr} \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} = -1$$

Substituting $\langle \mathbf{B}, \mathbf{A}_1 \rangle = 0, \langle \mathbf{B}, \mathbf{A}_2 \rangle = \frac{1}{\sqrt{2}}, \langle \mathbf{B}, \mathbf{A}_3 \rangle = -1, \mathbf{B} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \mathbf{A}_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix},$

$\mathbf{A}_2 = \begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix}$ and $\mathbf{A}_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ into

$$\mathbf{A}_4 = \mathbf{B} - \langle \mathbf{B}, \mathbf{A}_1 \rangle \mathbf{A}_1 - \langle \mathbf{B}, \mathbf{A}_2 \rangle \mathbf{A}_2 - \langle \mathbf{B}, \mathbf{A}_3 \rangle \mathbf{A}_3 \quad (**)$$

gives

$$\begin{aligned}
\mathbf{A}_4 &= \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} - 0 \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} - \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{pmatrix} - (-1) \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \\
&= \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \\
&= \begin{pmatrix} 0-0+0 & 1-1/2+0 \\ -1-0+1 & 0-1/2+0 \end{pmatrix} \\
&= \begin{pmatrix} 0 & 1/2 \\ 0 & -1/2 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 0 & -1 \end{pmatrix}
\end{aligned}$$

Remember we can ignore the fraction and let $\mathbf{A}'_4 = \begin{pmatrix} 0 & 1 \\ 0 & -1 \end{pmatrix}$. This matrix is orthogonal to $\{\mathbf{A}_1, \mathbf{A}_2, \mathbf{A}_3\}$. We only need to normalise \mathbf{A}'_4 :

$$\|\mathbf{A}'_4\| = \left\| \begin{pmatrix} 0 & 1 \\ 0 & -1 \end{pmatrix} \right\| = \sqrt{0^2 + 1^2 + 0^2 + (-1)^2} = \sqrt{2}$$

Hence the normalised matrix is

$$\mathbf{A}'_4 = \frac{1}{\|\mathbf{A}'_4\|} \mathbf{A}'_4 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 \\ 0 & -1 \end{pmatrix}$$

(e) How do we find the given scalars $\lambda_1, \lambda_2, \lambda_3, \lambda_4$?

By using:

Proposition (4-11). Let $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ be an **orthonormal** set of vectors and $\mathbf{u} \in V$ then

$$\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \langle \mathbf{u}, \mathbf{v}_3 \rangle \mathbf{v}_3 + \dots + \langle \mathbf{u}, \mathbf{v}_n \rangle \mathbf{v}_n$$

Let $\mathbf{C} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$. Note that \mathbf{C} is the identity matrix, that is $\mathbf{C} = \mathbf{I}$.

$$\mathbf{C} = \lambda_1 \mathbf{A}_1 + \lambda_2 \mathbf{A}_2 + \lambda_3 \mathbf{A}_3 + \lambda_4 \mathbf{A}'_4$$

where $\lambda_1 = \langle \mathbf{C}, \mathbf{A}_1 \rangle$, $\lambda_2 = \langle \mathbf{C}, \mathbf{A}_2 \rangle$, $\lambda_3 = \langle \mathbf{C}, \mathbf{A}_3 \rangle$ and $\lambda_4 = \langle \mathbf{C}, \mathbf{A}'_4 \rangle$.

Since $\mathbf{C} = \mathbf{I}$ we have for $k = 1, 2, 3$ and 4:

$$\begin{aligned}
\lambda_k &= \langle \mathbf{C}, \mathbf{A}_k \rangle = \langle \mathbf{I}, \mathbf{A}_k \rangle \\
&= \langle \mathbf{A}_k, \mathbf{I} \rangle = \text{tr}(\mathbf{I}^T \mathbf{A}_k) = \text{tr}(\mathbf{I} \mathbf{A}_k) = \text{tr}(\mathbf{A}_k)
\end{aligned}$$

We use this $\lambda_k = \text{tr}(\mathbf{A}_k)$ to find $\lambda_1, \lambda_2, \lambda_3, \lambda_4$:

$$\lambda_1 = \text{tr}[\mathbf{A}_1] = \text{tr} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = 1$$

$$\lambda_2 = \text{tr}[\mathbf{A}_2] = \text{tr} \begin{bmatrix} 0 & 1/\sqrt{2} \\ 0 & 1/\sqrt{2} \end{bmatrix} = \frac{1}{\sqrt{2}}$$

$$\lambda_3 = \text{tr}[\mathbf{A}_3] = \text{tr} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = 0$$

$$\lambda_4 = \text{tr}[\mathbf{A}'_4] = \text{tr} \left[\frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix} \right] = -\frac{1}{\sqrt{2}}$$

Hence $\lambda_1 = 1$, $\lambda_2 = \frac{1}{\sqrt{2}}$, $\lambda_3 = 0$ and $\lambda_4 = -\frac{1}{\sqrt{2}}$.

9. (a) The length of the vector $\mathbf{v} = 2\mathbf{q}_1 - 3\mathbf{q}_2 + 2\mathbf{q}_3$ is given by evaluating the norm of this vector. We have

$$\begin{aligned} \|\mathbf{v}\|^2 &= \langle 2\mathbf{q}_1 - 3\mathbf{q}_2 + 2\mathbf{q}_3, 2\mathbf{q}_1 - 3\mathbf{q}_2 + 2\mathbf{q}_3 \rangle \\ &= 4\langle \mathbf{q}_1, \mathbf{q}_1 \rangle + 9\langle \mathbf{q}_2, \mathbf{q}_2 \rangle + 4\langle \mathbf{q}_3, \mathbf{q}_3 \rangle \quad [\text{Because } \mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3 \text{ are orthonormal}] \\ &= 4\|\mathbf{q}_1\|^2 + 9\|\mathbf{q}_2\|^2 + 4\|\mathbf{q}_3\|^2 \\ &= 4(1) + 9(1) + 4(1) = 17 \quad [\text{Because } \mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3 \text{ are orthonormal}] \end{aligned}$$

Taking the square root gives $\|\mathbf{v}\| = \sqrt{17}$.

(b) We are given that $\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3$ are orthonormal vectors in \mathbb{R}^4 . We need to convert \mathbf{u} so that it is an orthogonal vector to $\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3$ by applying Gram-Schmidt (4-10):

$$\mathbf{w} = \mathbf{u} - \frac{\langle \mathbf{u}, \mathbf{q}_1 \rangle}{\|\mathbf{q}_1\|^2} \mathbf{q}_1 - \frac{\langle \mathbf{u}, \mathbf{q}_2 \rangle}{\|\mathbf{q}_2\|^2} \mathbf{q}_2 - \frac{\langle \mathbf{u}, \mathbf{q}_3 \rangle}{\|\mathbf{q}_3\|^2} \mathbf{q}_3$$

Since $\mathbf{q}_1, \mathbf{q}_2$ and \mathbf{q}_3 are orthonormal vectors therefore $\|\mathbf{q}_1\|^2 = \|\mathbf{q}_2\|^2 = \|\mathbf{q}_3\|^2 = 1$. Thus the above can be written as

$$\mathbf{w} = \mathbf{u} - \langle \mathbf{u}, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{u}, \mathbf{q}_2 \rangle \mathbf{q}_2 - \langle \mathbf{u}, \mathbf{q}_3 \rangle \mathbf{q}_3 \quad [\text{Because } \|\mathbf{q}_1\|^2 = \|\mathbf{q}_2\|^2 = \|\mathbf{q}_3\|^2 = 1]$$

However this vector \mathbf{w} is **not** normalized. *How do we normalize this?*

The normalized vector is given by

$$\mathbf{w} = \frac{\mathbf{w}}{\|\mathbf{w}\|} \quad \text{where } \mathbf{w} = \mathbf{u} - \langle \mathbf{u}, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{u}, \mathbf{q}_2 \rangle \mathbf{q}_2 - \langle \mathbf{u}, \mathbf{q}_3 \rangle \mathbf{q}_3$$

(c) We have $\mathbf{u} = 2\mathbf{q}_1 - 3\mathbf{q}_2 + 2\mathbf{q}_3$ which means that the vector \mathbf{u} is linearly dependent on $\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3$. Gram Schmidt **cannot** be applied to linearly **dependent** vectors.

10. Finding $\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3$ in \mathbb{R}^5 such that $\mathbf{w}_i \cdot \mathbf{w}_j = 0$ means that we need to find orthogonal vectors. *How?*

By using the Gram-Schmidt Process (4-10):

$$\mathbf{w}_1 = \mathbf{v}_1, \mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \text{ and } \mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

We have $\mathbf{w}_1 = \mathbf{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$. Substituting $\mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ and $\mathbf{w}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$ into $\langle \mathbf{v}_2, \mathbf{w}_1 \rangle$ gives

$$\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = 0 + 1 + 0 + 0 + 0 = 1$$

$$\|\mathbf{w}_1\|^2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = 0^2 + 1^2 + 0^2 + 1^2 + 0^2 = 2$$

Hence we have

$$\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0-0 \\ 1-1/2 \\ 1-0 \\ 0-1/2 \\ 0-0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1/2 \\ 1 \\ -1/2 \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 2 \\ -1 \\ 0 \end{bmatrix}$$

Ignore the fraction and let $\mathbf{w}'_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \\ -1 \\ 0 \end{bmatrix}$. What else do we need to find?

The vector \mathbf{w}_3 which is given by $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2$:

$$\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = 0 + 1 + 0 + 1 + 0 = 2$$

$$\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 2 \\ -1 \\ 0 \end{bmatrix} = 0 + 1 + 0 - 1 + 0 = 0$$

We do **not** need to evaluate the remaining parts because $\langle \mathbf{v}_3, \mathbf{w}'_2 \rangle = 0$ which means

$$\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{0}{\|\mathbf{w}'_2\|^2} \mathbf{w}'_2 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1:$$

$$\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} - \frac{2}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0-0 \\ 1-1 \\ 0-0 \\ 1-1 \\ 1-0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Thus our orthogonal vectors are $\mathbf{w}_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{w}'_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \\ -1 \\ 0 \end{bmatrix}$ and $\mathbf{w}_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$.

11. (a) and (b). We need to find the vectors $\mathbf{v} = [v_1, v_2]$ and $\mathbf{w} = [w_1, w_2]$ such that

$$\langle \mathbf{v}, \mathbf{w} \rangle = 3v_1w_1 + 2v_2w_2 = 0$$

Rearranging this we have

$$3v_1w_1 = -2v_2w_2$$

$$v_1w_1 = -\frac{2}{3}v_2w_2$$

Let $v_2w_2 = -3$. Let $v_2 = -1$ and $w_2 = 3$. For these values we have $v_1w_1 = 2$. Let $v_1 = 2$ and $w_1 = 1$. Our vectors are

$$\mathbf{v} = [v_1, v_2] = [2, -1] \text{ and } \mathbf{w} = [w_1, w_2] = [1, 3]$$

Since we are given that dot product of $\mathbf{v} = [v_1, v_2]$ and $\mathbf{w} = [w_1, w_2]$ is **not** zero which means that:

$$\langle \mathbf{v}, \mathbf{w} \rangle = v_1w_1 + v_2w_2 \neq 0$$

We need to check this holds for $\mathbf{v} = [2, -1]$ and $\mathbf{w} = [1, 3]$:

$$\begin{aligned} \langle \mathbf{v}, \mathbf{w} \rangle &= v_1w_1 + v_2w_2 \\ &= (2 \times 1) + (-1 \times 3) = -1 \neq 0 \end{aligned}$$

12. To find an orthonormal basis we apply Gram-Schmidt Process (4-10) which is

$$\mathbf{w}_1 = \mathbf{v}_1, \mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \text{ and } \mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

The given inner product is $\langle \mathbf{f}, \mathbf{g} \rangle = \int_{-1}^1 f(x)g(x)dx$.

We need to find an orthonormal basis of space V spanned by $\{\mathbf{1}, \mathbf{x}\}$.

Let $\mathbf{w}_1 = \mathbf{v}_1 = \mathbf{1}$ and $\mathbf{v}_2 = \mathbf{x}$. We need to determine $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\begin{aligned}
\langle \mathbf{v}_2, \mathbf{w}_1 \rangle &= \langle \mathbf{x}, \mathbf{1} \rangle \\
&= \int_{-1}^1 x(1) dx \\
&= \left[\frac{x^2}{2} \right]_{-1}^1 = \frac{1}{2}[1-1] = 0
\end{aligned}$$

This means that our given vectors were already orthogonal. Since $\mathbf{v}_2 = \mathbf{x}$ and $\mathbf{w}_1 = \mathbf{1}$ are orthogonal therefore $\mathbf{w}_2 = \mathbf{v}_2 = \mathbf{x}$.

Our orthogonal basis is $\{\mathbf{1}, \mathbf{x}\}$. We need to normalise these vectors to obtain a set of orthonormal basis.

Evaluating $\|\mathbf{w}_1\|^2$:

$$\begin{aligned}
\|\mathbf{w}_1\|^2 &= \langle \mathbf{1}, \mathbf{1} \rangle \\
&= \int_{-1}^1 (1 \times 1) dx = [x]_{-1}^1 = 1 - (-1) = 2 \\
\mathbf{w}_1 &= \frac{\mathbf{w}_1}{\|\mathbf{w}_1\|} = \frac{1}{\sqrt{2}} \quad \left[\text{Because } \|\mathbf{w}_1\|^2 = 2 \text{ from above} \right]
\end{aligned}$$

Similarly we have $\mathbf{w}_2 = \frac{\mathbf{w}_2}{\|\mathbf{w}_2\|}$. From above $\mathbf{w}_2 = \mathbf{x}$ but we need to find $\|\mathbf{w}_2\|$:

$$\begin{aligned}
\|\mathbf{w}_2\|^2 &= \langle \mathbf{x}, \mathbf{x} \rangle \\
&= \int_{-1}^1 xx dx \\
&= \int_{-1}^1 x^2 dx = \left[\frac{x^3}{3} \right]_{-1}^1 = \frac{1}{3}[1 - (-1)^3] = \frac{2}{3}
\end{aligned}$$

Taking the square root gives $\|\mathbf{w}_2\| = \sqrt{\frac{2}{3}}$. Substituting $\mathbf{w}_2 = \mathbf{x}$ and $\|\mathbf{w}_2\| = \sqrt{\frac{2}{3}}$ into

$\mathbf{w}_2 = \frac{\mathbf{w}_2}{\|\mathbf{w}_2\|}$ gives

$$\mathbf{w}_2 = \frac{\mathbf{x}}{\sqrt{2/3}} = \sqrt{\frac{3}{2}}\mathbf{x}$$

Hence our orthonormal basis is $\left\{ \frac{1}{\sqrt{2}}, \sqrt{\frac{3}{2}}\mathbf{x} \right\}$.

13. (a) We first need to show that $\langle \mathbf{A}, \mathbf{B} \rangle = \text{tr}(\mathbf{A}^T \mathbf{B})$ is an inner product ($\text{tr}(\)$ is the trace of the matrix).

By definition (4-1) an inner product satisfies:

(a) $\langle \mathbf{u}, \mathbf{v} \rangle = \langle \mathbf{v}, \mathbf{u} \rangle$ [Commutative Law]

(b) $\langle \mathbf{u} + \mathbf{v}, \mathbf{w} \rangle = \langle \mathbf{u}, \mathbf{w} \rangle + \langle \mathbf{v}, \mathbf{w} \rangle$ [Distributive Law]

(c) $\langle k\mathbf{u}, \mathbf{v} \rangle = k \langle \mathbf{u}, \mathbf{v} \rangle$

(d) $\langle \mathbf{u}, \mathbf{u} \rangle \geq 0$ and we have $\langle \mathbf{u}, \mathbf{u} \rangle = 0$ if and only if $\mathbf{u} = \mathbf{O}$

Checking (a):

$$\begin{aligned} \mathbf{A} &= \begin{bmatrix} a & b \\ c & d \end{bmatrix} \text{ and } \mathbf{B} = \begin{bmatrix} e & f \\ g & h \end{bmatrix} \text{ then} \\ \langle \mathbf{A}, \mathbf{B} \rangle &= \text{tr}(\mathbf{A}^T \mathbf{B}) \\ &= \text{tr} \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}^T \begin{bmatrix} e & f \\ g & h \end{bmatrix} \right) \\ &= \text{tr} \left(\begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} e & f \\ g & h \end{bmatrix} \right) \\ &= \text{tr} \begin{pmatrix} ae + cg & * \\ ** & bf + dh \end{pmatrix} = ae + cg + bf + dh \end{aligned}$$

The * and ** signify that we do **not** need to evaluate these entries because the trace of a matrix is the addition of the leading diagonal elements.

Evaluating $\langle \mathbf{B}, \mathbf{A} \rangle = \text{tr}(\mathbf{B}^T \mathbf{A})$:

$$\begin{aligned} \langle \mathbf{B}, \mathbf{A} \rangle &= \text{tr}(\mathbf{B}^T \mathbf{A}) \\ &= \text{tr} \left(\begin{bmatrix} e & f \\ g & h \end{bmatrix}^T \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) \\ &= \text{tr} \left(\begin{bmatrix} e & g \\ f & h \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) \\ &= \text{tr} \begin{pmatrix} ae + gc & \dagger \\ \dagger\dagger & fb + hd \end{pmatrix} = ae + gc + fb + hd = \langle \mathbf{A}, \mathbf{B} \rangle \quad [\text{From Above}] \end{aligned}$$

Hence we have $\langle \mathbf{A}, \mathbf{B} \rangle = \langle \mathbf{B}, \mathbf{A} \rangle$ which means that (a) holds.

Checking (b):

We are assuming $\text{tr}(\mathbf{A} + \mathbf{B}) = \text{tr}(\mathbf{A}) + \text{tr}(\mathbf{B})$. Let $\mathbf{C} \in M_{2,2}(\square)$:

$$\begin{aligned} \langle \mathbf{A} + \mathbf{B}, \mathbf{C} \rangle &= \text{tr}[(\mathbf{A} + \mathbf{B})^T \mathbf{C}] \\ &= \text{tr}[(\mathbf{A}^T + \mathbf{B}^T) \mathbf{C}] \quad \left[\text{Because } (\mathbf{A} + \mathbf{B})^T = \mathbf{A}^T + \mathbf{B}^T \right] \\ &= \text{tr}[\mathbf{A}^T \mathbf{C} + \mathbf{B}^T \mathbf{C}] \\ &= \text{tr}[\mathbf{A}^T \mathbf{C}] + \text{tr}[\mathbf{B}^T \mathbf{C}] = \langle \mathbf{A}, \mathbf{C} \rangle + \langle \mathbf{B}, \mathbf{C} \rangle \end{aligned}$$

We have $\langle \mathbf{A} + \mathbf{B}, \mathbf{C} \rangle = \langle \mathbf{A}, \mathbf{C} \rangle + \langle \mathbf{B}, \mathbf{C} \rangle$ which means that part (b) holds.

Checking (c):

We assume $\text{tr}((k\mathbf{A})\mathbf{B}) = k[\text{tr}(\mathbf{A}\mathbf{B})]$:

$$\begin{aligned} \langle k\mathbf{A}, \mathbf{B} \rangle &= \text{tr}((k\mathbf{A})^T, \mathbf{B}) \\ &= \text{tr}(k\mathbf{A}^T, \mathbf{B}) = k[\text{tr}(\mathbf{A}^T, \mathbf{B})] = k\langle \mathbf{A}, \mathbf{B} \rangle \end{aligned}$$

Since we have $\langle k\mathbf{A}, \mathbf{B} \rangle = k\langle \mathbf{A}, \mathbf{B} \rangle$ therefore part (c) holds.

Checking (d):

We have

$$\begin{aligned}
 \langle \mathbf{A}, \mathbf{A} \rangle &= \text{tr}(\mathbf{A}^T \mathbf{A}) \\
 &= \text{tr} \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}^T \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) \\
 &= \text{tr} \left(\begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) \\
 &= \text{tr} \left(\begin{bmatrix} a^2 + c^2 & ? \\ ?? & b^2 + d^2 \end{bmatrix} \right) = a^2 + c^2 + b^2 + d^2 \geq 0
 \end{aligned}$$

This means $\langle \mathbf{A}, \mathbf{A} \rangle = a^2 + c^2 + b^2 + d^2 \geq 0$. Also

$$\langle \mathbf{A}, \mathbf{A} \rangle = a^2 + c^2 + b^2 + d^2 = 0 \Leftrightarrow a = b = c = d = 0$$

With $a = b = c = d = 0$ which means we have $\mathbf{A} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \mathbf{O}$.

Hence part (d) holds.

Since all four parts (a), (b), (c) and (d) of definition (4-1) is satisfied therefore

$\langle \mathbf{A}, \mathbf{B} \rangle = \text{tr}(\mathbf{A}^T \mathbf{B})$ is an inner product on $M_{2,2}(\mathbb{R})$.

(b) The distance between $\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix}$ and $\mathbf{B} = \begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix}$ is given by

$$\|\mathbf{A} - \mathbf{B}\|^2 = \langle \mathbf{A} - \mathbf{B}, \mathbf{A} - \mathbf{B} \rangle \quad (*)$$

Carrying out the subtraction $\mathbf{A} - \mathbf{B} = \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix} - \begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} -2 & -1 \\ 0 & -2 \end{bmatrix}$. Substituting this into

(*) gives

$$\begin{aligned}
 \|\mathbf{A} - \mathbf{B}\|^2 &= \left\langle \begin{bmatrix} -2 & -1 \\ 0 & -2 \end{bmatrix}, \begin{bmatrix} -2 & -1 \\ 0 & -2 \end{bmatrix} \right\rangle \\
 &= \text{tr} \left(\begin{bmatrix} -2 & -1 \\ 0 & -2 \end{bmatrix}^T \begin{bmatrix} -2 & -1 \\ 0 & -2 \end{bmatrix} \right) \\
 &= \text{tr} \left(\begin{bmatrix} -2 & 0 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} -2 & -1 \\ 0 & -2 \end{bmatrix} \right) \\
 &= \text{tr} \left(\begin{bmatrix} 4 & 2 \\ 2 & 5 \end{bmatrix} \right) = 4 + 5 = 9
 \end{aligned}$$

Taking the square root gives $\|\mathbf{A} - \mathbf{B}\| = \sqrt{9} = 3$.

(c) The angle θ between $\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix}$ and $\mathbf{B} = \begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix}$ is given by

$$\cos(\theta) = \frac{\langle \mathbf{A}, \mathbf{B} \rangle}{\|\mathbf{A}\| \|\mathbf{B}\|} \quad (\text{f})$$

We can evaluate each component:

$$\begin{aligned}
\|\mathbf{A}\|^2 &= \langle \mathbf{A}, \mathbf{A} \rangle = \text{tr}(\mathbf{A}^T \mathbf{A}) \\
&= \text{tr} \left(\begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix}^T \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix} \right) \\
&= \text{tr} \left(\begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix} \right) = \text{tr} \begin{pmatrix} 2 & 2 \\ 2 & 4 \end{pmatrix} = 2 + 4 = 6
\end{aligned}$$

Taking the square root gives $\|\mathbf{A}\| = \sqrt{6}$. Similarly we have

$$\begin{aligned}
\|\mathbf{B}\|^2 &= \langle \mathbf{B}, \mathbf{B} \rangle = \text{tr}(\mathbf{B}^T \mathbf{B}) \\
&= \text{tr} \left(\begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix}^T \begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix} \right) \\
&= \text{tr} \left(\begin{bmatrix} 3 & 1 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix} \right) = \text{tr} \begin{pmatrix} 10 & 11 \\ 11 & 13 \end{pmatrix} = 10 + 13 = 23
\end{aligned}$$

Taking the square root gives $\|\mathbf{B}\| = \sqrt{23}$.

Evaluating out the numerator in the above (£):

$$\begin{aligned}
\langle \mathbf{A}, \mathbf{B} \rangle &= \text{tr}(\mathbf{A}^T \mathbf{B}) \\
&= \text{tr} \left(\begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix}^T \begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix} \right) \\
&= \text{tr} \left(\begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix} \right) = \text{tr} \begin{pmatrix} 4 & 5 \\ 6 & 6 \end{pmatrix} = 4 + 6 = 10
\end{aligned}$$

Substituting $\|\mathbf{A}\| = \sqrt{6}$, $\|\mathbf{B}\| = \sqrt{23}$ and $\langle \mathbf{A}, \mathbf{B} \rangle = 10$ into (£) gives:

$$\cos(\theta) = \frac{\langle \mathbf{A}, \mathbf{B} \rangle}{\|\mathbf{A}\| \|\mathbf{B}\|} = \frac{10}{\sqrt{6}\sqrt{23}}$$

Taking inverse cos yields:

$$\theta = \cos^{-1} \left(\frac{10}{\sqrt{6}\sqrt{23}} \right) = 31.65^\circ$$

14. We are given that $\mathbf{f}(t) = c_0 + c_1 t + c_2 t^2$ and $\mathbf{f}\left(\frac{1}{2}\right) = 0$. Substituting $t = \frac{1}{2}$ into

$\mathbf{f}(t) = c_0 + c_1 t + c_2 t^2$ gives

$$\mathbf{f}\left(\frac{1}{2}\right) = c_0 + c_1 \left(\frac{1}{2}\right) + c_2 \left(\frac{1}{2}\right)^2 = c_0 + \frac{c_1}{2} + \frac{c_2}{4} = 0$$

Multiplying both sides by 4 gives

$$4c_0 + 2c_1 + c_2 = 0 \Rightarrow c_2 = -4c_0 - 2c_1 \quad (*)$$

We are also given that $\mathbf{f}(t) = c_0 + c_1 t + c_2 t^2$ is orthogonal to $1 + t$:

$$\begin{aligned}
\langle 1+t, c_0 + c_1 t + c_2 t^2 \rangle &= \int_0^1 (1+t)(c_0 + c_1 t + c_2 t^2) dt \\
&= \int_0^1 [(c_0 + c_1 t + c_2 t^2) + (c_0 t + c_1 t^2 + c_2 t^3)] dt \\
&= \int_0^1 [c_0 + (c_1 + c_0)t + (c_2 + c_1)t^2 + c_2 t^3] dt \\
&= \left[c_0 t + \frac{(c_1 + c_0)t^2}{2} + \frac{(c_2 + c_1)t^3}{3} + \frac{c_2 t^4}{4} \right]_0^1 \\
&= c_0 + \frac{(c_1 + c_0)}{2} + \frac{(c_2 + c_1)}{3} + \frac{c_2}{4} = 0 \quad [\text{Because of orthogonality}]
\end{aligned}$$

Multiplying the last equation by 12 gives

$$\begin{aligned}
12c_0 + 6(c_1 + c_0) + 4(c_2 + c_1) + 3c_2 &= 0 \\
18c_0 + 10c_1 + 7c_2 &= 0
\end{aligned}$$

Substituting $c_2 = -4c_0 - 2c_1$ which is (*) above into this last equation

$$18c_0 + 10c_1 + 7c_2 = 0:$$

$$\begin{aligned}
18c_0 + 10c_1 + 7(-4c_0 - 2c_1) &= 0 \\
-10c_0 - 4c_1 &= 0 \\
c_1 &= -\frac{10}{4}c_0
\end{aligned}$$

Let $c_0 = 4$ then $c_1 = -\frac{10}{4}(4) = -10$. Substituting $c_0 = 4$ and $c_1 = -10$ into

$c_2 = -4c_0 - 2c_1$ gives

$$c_2 = -4(4) - 2(-10) = 4$$

Thus we have $c_0 = 4$, $c_1 = -10$ and $c_2 = 4$ which yields that

$$\mathbf{f}(t) = c_0 + c_1 t + c_2 t^2 = 4 - 10t + 4t^2$$

A basis for the given subspace S is $\{\mathbf{f}(t) = 4 - 10t + 4t^2\}$.

15. We can start with standard basis for P_2 which is the set of all quadratic polynomials and then apply Gram-Schmidt process to convert into an orthogonal basis. *What is the standard basis for P_2 ?*

$\{\mathbf{1}, \mathbf{x}, \mathbf{x}^2\}$. Let $\mathbf{v}_1 = \mathbf{1}$, $\mathbf{v}_2 = \mathbf{x}$ and $\mathbf{v}_3 = \mathbf{x}^2$. Gram-Schmidt Process (4-10) is

$$\mathbf{w}_1 = \mathbf{v}_1, \quad \mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \quad \text{and} \quad \mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

The inner product is given by $\langle \mathbf{f}, \mathbf{g} \rangle = \int_0^1 \mathbf{f}(x) \mathbf{g}(1-x) dx$.

We have $\mathbf{w}_1 = \mathbf{v}_1 = \mathbf{1}$. We need to determine \mathbf{w}_2 by using the above formula. We have $\mathbf{v}_2 = \mathbf{x}$ and $\mathbf{w}_1 = 1$ which means that we can evaluate

$$\begin{aligned}
\langle \mathbf{v}_2, \mathbf{w}_1 \rangle &= \langle \mathbf{x}, \mathbf{1} \rangle = \int_0^1 x(1) dx \\
&= \int_0^1 x dx = \left[\frac{x^2}{2} \right]_0^1 = \frac{1}{2} \\
\|\mathbf{w}_1\|^2 &= \langle \mathbf{1}, \mathbf{1} \rangle = \int_0^1 1 dx = [x]_0^1 = 1
\end{aligned}$$

Substituting $\mathbf{v}_2 = \mathbf{x}$, $\mathbf{w}_1 = \mathbf{1}$, $\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = \frac{1}{2}$ and $\|\mathbf{w}_1\|^2 = 1$ into $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\mathbf{w}_2 = \mathbf{x} - \frac{1}{2}(\mathbf{1}) = \mathbf{x} - \frac{1}{2}$$

What else do we need to find?

$$\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

Evaluating each of the components gives:

$$\begin{aligned}
\langle \mathbf{v}_3, \mathbf{w}_1 \rangle &= \langle \mathbf{x}^2, \mathbf{1} \rangle = \int_0^1 x^2(1) dx \\
&= \left[\frac{x^3}{3} \right]_0^1 = \frac{1}{3}
\end{aligned}$$

In the next two evaluations we need to find $\mathbf{g}(1-x)$ given that $\mathbf{g}(x) = x - \frac{1}{2}$:

$$\mathbf{g}(1-x) = 1-x - \frac{1}{2} = \frac{1}{2} - x \quad (\dagger)$$

We have

$$\begin{aligned}
\langle \mathbf{v}_3, \mathbf{w}_2 \rangle &= \left\langle \mathbf{x}^2, \mathbf{x} - \frac{1}{2} \right\rangle && \left[\text{Because } \mathbf{w}_2 = \mathbf{x} - \frac{1}{2} \text{ from above} \right] \\
&= \int_0^1 x^2 \left(\frac{1}{2} - x \right) dx && [\text{By } (\dagger)] \\
&= \int_0^1 \left(\frac{x^2}{2} - x^3 \right) dx \\
&= \left[\frac{x^3}{6} - \frac{x^4}{4} \right]_0^1 \underset{\text{Substituting Limits}}{=} = \frac{1}{6} - \frac{1}{4} = -\frac{1}{12}
\end{aligned}$$

Also

$$\begin{aligned}
\|\mathbf{w}_2\|^2 &= \langle \mathbf{w}_2, \mathbf{w}_2 \rangle \\
&= \left\langle \mathbf{x} - \frac{1}{2}, \mathbf{x} - \frac{1}{2} \right\rangle \\
&= \int_0^1 \left(x - \frac{1}{2} \right) \left(\frac{1}{2} - x \right) dx \\
&= \int_0^1 \left(\frac{1}{2}x - x^2 - \frac{1}{4} + \frac{1}{2}x \right) dx \\
&= \int_0^1 \left(x - x^2 - \frac{1}{4} \right) dx = \left[\frac{x^2}{2} - \frac{x^3}{3} - \frac{x}{4} \right]_0^1 = \frac{1}{2} - \frac{1}{3} - \frac{1}{4} = -\frac{1}{12}
\end{aligned}$$

Substituting $\mathbf{v}_3 = \mathbf{x}^2$, $\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = \frac{1}{3}$, $\|\mathbf{w}_1\|^2 = 1$, $\mathbf{w}_1 = \mathbf{1}$, $\langle \mathbf{v}_3, \mathbf{w}_2 \rangle = -\frac{1}{12}$, $\|\mathbf{w}_2\|^2 = -\frac{1}{12}$

and $\mathbf{w}_2 = \mathbf{x} - \frac{1}{2}$ into $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$ gives

$$\begin{aligned}
\mathbf{w}_3 &= \mathbf{x}^2 - \frac{1}{3}(\mathbf{1}) - \frac{-1/12}{-1/12} \left(\mathbf{x} - \frac{1}{2} \right) \\
&= \mathbf{x}^2 - \frac{1}{3} - \left(\mathbf{x} - \frac{1}{2} \right) = \mathbf{x}^2 - \mathbf{x} + \frac{1}{6}
\end{aligned}$$

Our orthogonal basis is $\left\{ \mathbf{1}, \mathbf{x} - \frac{1}{2}, \mathbf{x}^2 - \mathbf{x} + \frac{1}{6} \right\}$.

16. We need to show why $\langle \mathbf{A}, \mathbf{B} \rangle = \text{tr}(\mathbf{AB})$ is **not** an inner product.

Let $\mathbf{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. We can check that part (d) of definition (4-1) does **not** hold, that is

(d) $\langle \mathbf{u}, \mathbf{u} \rangle \geq 0$ and we have $\langle \mathbf{u}, \mathbf{u} \rangle = 0$ if and only if $\mathbf{u} = \mathbf{0}$

It is enough to show that for particular entries a, b, c and d of matrix \mathbf{A} we have

$\langle \mathbf{A}, \mathbf{A} \rangle < 0$. Evaluating $\langle \mathbf{A}, \mathbf{A} \rangle$ by using $\langle \mathbf{A}, \mathbf{B} \rangle = \text{tr}(\mathbf{AB})$:

$$\begin{aligned}
\langle \mathbf{A}, \mathbf{A} \rangle &= \text{tr}(\mathbf{AA}) \\
&= \text{tr} \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) \\
&= \text{tr} \begin{pmatrix} a^2 + bc & * \\ ** & cb + d^2 \end{pmatrix} = a^2 + bc + cb + d^2 = a^2 + 2bc + d^2
\end{aligned}$$

Now chose any values of a, b, c and d so that $2bc < a^2 + d^2$. For example let $a = d = 1$ and $b = 1, c = -2$ then from above we have

$$\langle \mathbf{A}, \mathbf{A} \rangle = a^2 + 2bc + d^2 = 1^2 + 2(1)(-2) + 1^2 = -2 < 0$$

Hence we have $\langle \mathbf{A}, \mathbf{A} \rangle < 0$ which means that part (d) of definition (4-1) fails so

$\langle \mathbf{A}, \mathbf{B} \rangle = \text{tr}(\mathbf{AB})$ **cannot** be an inner product.

17. Remember Proposition (4-11) is:

Let $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ be an **orthonormal** set of vectors in an inner product space V of dimension n . Let $\mathbf{u} \in V$ then

$$\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \langle \mathbf{u}, \mathbf{v}_3 \rangle \mathbf{v}_3 + \dots + \langle \mathbf{u}, \mathbf{v}_n \rangle \mathbf{v}_n$$

Proof.

Since $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ is an **orthonormal** set of vectors so they are linearly independent which means that they form a basis for the inner product space V because V has dimension n . Let $\mathbf{u} \in V$ then there exists scalars $k_1, k_2, k_3, \dots, k_n$ such that

$$\mathbf{u} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_3 + \dots + k_n \mathbf{v}_n \quad (*)$$

Required to prove that $k_j = \langle \mathbf{u}, \mathbf{v}_j \rangle$ for $j = 1, 2, 3, \dots, n$. Consider the inner product $\langle \mathbf{u}, \mathbf{v}_j \rangle$ for any $j = 1, 2, 3, \dots, n$:

$$\begin{aligned} \langle \mathbf{u}, \mathbf{v}_j \rangle &= \langle k_1 \mathbf{v}_1 + \dots + k_j \mathbf{v}_j + \dots + k_n \mathbf{v}_n, \mathbf{v}_j \rangle \quad [\text{By } (*) \quad \mathbf{u} = k_1 \mathbf{v}_1 + \dots + k_n \mathbf{v}_n] \\ &= k_1 \langle \mathbf{v}_1, \mathbf{v}_j \rangle + \dots + k_j \langle \mathbf{v}_j, \mathbf{v}_j \rangle + \dots + k_n \langle \mathbf{v}_n, \mathbf{v}_j \rangle \\ &= k_1 (0) + \dots + k_j \|\mathbf{v}_j\|^2 + \dots + k_n (0) \quad [\{\mathbf{v}_1, \dots, \mathbf{v}_n\} \text{ are orthogonal}] \\ &= k_j \|\mathbf{v}_j\|^2 = k_j (1) = k_j \quad [\text{Because } \mathbf{v}_j \text{ is orthonormal}] \end{aligned}$$

Hence we have shown that $k_j = \langle \mathbf{u}, \mathbf{v}_j \rangle$ for any $j = 1, 2, 3, \dots, n$. Substituting this $k_j = \langle \mathbf{u}, \mathbf{v}_j \rangle$ into $(*)$ gives us our required result:

$$\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \langle \mathbf{u}, \mathbf{v}_3 \rangle \mathbf{v}_3 + \dots + \langle \mathbf{u}, \mathbf{v}_n \rangle \mathbf{v}_n$$

■

18. We need to use Gram-Schmidt Process (4-10) which is:

$$\mathbf{w}_1 = \mathbf{v}_1, \mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \text{ and } \mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$$

Let $\mathbf{v}_1 = \mathbf{1}$, $\mathbf{v}_2 = \mathbf{x}$, $\mathbf{v}_3 = \mathbf{x}^2$, $\mathbf{v}_4 = \mathbf{x}^3$. Applying Gram-Schmidt we have $\mathbf{w}_1 = \mathbf{v}_1 = \mathbf{1}$.

The inner product is given by $\langle \mathbf{f}, \mathbf{g} \rangle = \int_{-1}^1 f(x) g(x) dx$. We need to find

$$\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 \text{ by evaluating each component:}$$

$$\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = \langle \mathbf{x}, \mathbf{1} \rangle$$

$$= \int_{-1}^1 x(1) dx = \left[\frac{x^2}{2} \right]_{-1}^1 \underset{\text{Substituting Limits}}{=} = \frac{1}{2} [1^2 - (-1)^2] = 0$$

What does the zero result signify?

Means that \mathbf{x} and $\mathbf{1}$ are already orthogonal therefore $\mathbf{w}_2 = \mathbf{x}$.

Next we determine each of the components of $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$:

$$\begin{aligned}
\langle \mathbf{v}_3, \mathbf{w}_1 \rangle &= \langle \mathbf{x}^2, \mathbf{1} \rangle \\
&= \int_{-1}^1 x^2 (1) dx = \left[\frac{x^3}{3} \right]_{-1}^1 \underset{\text{Substituting Limits}}{=} \frac{1}{3} [1^3 - (-1)^3] = \frac{2}{3} \\
\|\mathbf{w}_1\|^2 &= \langle \mathbf{w}_1, \mathbf{w}_1 \rangle \\
&= \langle \mathbf{1}, \mathbf{1} \rangle = \int_{-1}^1 1(1) dx = [x]_{-1}^1 \underset{\text{Substituting Limits}}{=} [1 - (-1)] = 2 \\
\langle \mathbf{v}_3, \mathbf{w}_2 \rangle &= \langle \mathbf{x}^2, \mathbf{x} \rangle \\
&= \int_{-1}^1 x^2 (x) dx = \int_{-1}^1 x^3 dx = \left[\frac{x^4}{4} \right]_{-1}^1 \underset{\text{Substituting Limits}}{=} \frac{1}{4} [1^4 - (-1)^4] = 0
\end{aligned}$$

As above this $\langle \mathbf{v}_3, \mathbf{w}_2 \rangle = \langle \mathbf{x}^2, \mathbf{x} \rangle = 0$ means \mathbf{x}^2 and \mathbf{x} are orthogonal.

Substituting $\mathbf{v}_3 = \mathbf{x}^2$, $\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = \frac{2}{3}$, $\|\mathbf{w}_1\|^2 = 2$, $\mathbf{w}_1 = \mathbf{1}$ and $\langle \mathbf{v}_3, \mathbf{w}_2 \rangle = 0$ into

$\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$ gives

$$\begin{aligned}
\mathbf{w}_3 &= \mathbf{x}^2 - \frac{2/3}{2} (\mathbf{1}) - 0 \mathbf{w}_2 \\
&= \mathbf{x}^2 - \frac{1}{3}
\end{aligned}$$

What else do we need to find?

\mathbf{w}_4 which is given by $\mathbf{w}_4 = \mathbf{v}_4 - \frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2 - \frac{\langle \mathbf{v}_4, \mathbf{w}_3 \rangle}{\|\mathbf{w}_3\|^2} \mathbf{w}_3$. Evaluating each of these we have

$$\begin{aligned}
\langle \mathbf{v}_4, \mathbf{w}_1 \rangle &= \langle \mathbf{x}^3, \mathbf{1} \rangle \\
&= \int_{-1}^1 x^3 (1) dx = \left[\frac{x^4}{4} \right]_{-1}^1 = \frac{1}{4} [1^4 - (-1)^4] = 0 \\
\langle \mathbf{v}_4, \mathbf{w}_2 \rangle &= \langle \mathbf{x}^3, \mathbf{x} \rangle \\
&= \int_{-1}^1 x^3 (x) dx = \left[\frac{x^5}{5} \right]_{-1}^1 = \frac{1}{5} [1^5 - (-1)^5] = \frac{2}{5} \\
\langle \mathbf{v}_4, \mathbf{w}_3 \rangle &= \left\langle \mathbf{x}^3, \mathbf{x}^2 - \frac{1}{3} \right\rangle \\
&= \int_{-1}^1 x^3 \left(x^2 - \frac{1}{3} \right) dx \\
&= \int_{-1}^1 \left(x^5 - \frac{x^3}{3} \right) dx \\
&= \left[\frac{x^6}{6} - \frac{x^4}{12} \right]_{-1}^1 = \frac{1}{12} [2(1)^6 - (1)^4 - (2(-1)^6 - (-1)^4)] = 0
\end{aligned}$$

$$\begin{aligned}
\|\mathbf{w}_2\|^2 &= \langle \mathbf{w}_2, \mathbf{w}_2 \rangle \\
&= \langle \mathbf{x}, \mathbf{x} \rangle \\
&= \int_{-1}^1 x(x) dx \\
&= \int_{-1}^1 x^2 dx = \left[\frac{x^3}{3} \right]_{-1}^1 = \frac{1}{3} [1^3 - (-1)^3] = \frac{2}{3}
\end{aligned}$$

Substituting $\mathbf{v}_4 = \mathbf{x}^3$, $\langle \mathbf{v}_4, \mathbf{w}_1 \rangle = 0$, $\langle \mathbf{v}_4, \mathbf{w}_2 \rangle = \frac{2}{5}$, $\|\mathbf{w}_2\|^2 = \frac{2}{3}$, $\mathbf{w}_2 = \mathbf{x}$ and

$$\begin{aligned}
\langle \mathbf{v}_4, \mathbf{w}_3 \rangle = 0 \text{ into } \mathbf{w}_4 &= \mathbf{v}_4 - \frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2 - \frac{\langle \mathbf{v}_4, \mathbf{w}_3 \rangle}{\|\mathbf{w}_3\|^2} \mathbf{w}_3 \text{ gives} \\
\mathbf{w}_4 &= \mathbf{x}^3 - 0\mathbf{w}_1 - \frac{2/5}{2/3} \mathbf{x} - 0\mathbf{w}_3 \\
&= \mathbf{x}^3 - \frac{3}{5} \mathbf{x}
\end{aligned}$$

Thus our orthogonal vectors are $\mathbf{w}_1 = \mathbf{1}$, $\mathbf{w}_2 = \mathbf{x}$, $\mathbf{w}_3 = \mathbf{x}^2 - \frac{1}{3}$ and $\mathbf{w}_4 = \mathbf{x}^3 - \frac{3}{5} \mathbf{x}$.

How do we find an orthonormal basis?

We need to normalise these vectors:

$$\begin{aligned}
\mathbf{w}_1 &= \frac{1}{\|\mathbf{w}_1\|} \mathbf{w}_1 = \frac{1}{\sqrt{2}} (\mathbf{1}) \\
\mathbf{w}_2 &= \frac{1}{\|\mathbf{w}_2\|} \mathbf{w}_2 = \frac{1}{\sqrt{2/3}} (\mathbf{x}) = \sqrt{\frac{3}{2}} \mathbf{x} \quad \left[\text{Because } \|\mathbf{w}_2\|^2 = \frac{2}{3} \right]
\end{aligned}$$

For the remaining two vectors we need to find $\|\mathbf{w}_3\|$ and $\|\mathbf{w}_4\|$:

$$\begin{aligned}
\|\mathbf{w}_3\|^2 &= \langle \mathbf{w}_3, \mathbf{w}_3 \rangle \\
&= \left\langle \mathbf{x}^2 - \frac{1}{3}, \mathbf{x}^2 - \frac{1}{3} \right\rangle \\
&= \int_{-1}^1 \left(x^2 - \frac{1}{3} \right) \left(x^2 - \frac{1}{3} \right) dx \\
&= \int_{-1}^1 \left(x^4 - \frac{2}{3} x^2 + \frac{1}{9} \right) dx \\
&= \left[\frac{x^5}{5} - \frac{2x^3}{9} + \frac{x}{9} \right]_{-1}^1 \\
&= \left(\frac{1^5}{5} - \frac{2(1)^3}{9} + \frac{1}{9} \right) - \left(\frac{(-1)^5}{5} - \frac{2(-1)^3}{9} - \frac{1}{9} \right) = \frac{8}{45}
\end{aligned}$$

Taking the square root gives $\|\mathbf{w}_3\| = \sqrt{\frac{8}{45}}$. Similarly we have

$$\begin{aligned}
\|\mathbf{w}_4\|^2 &= \langle \mathbf{w}_4, \mathbf{w}_4 \rangle \\
&= \left\langle \mathbf{x}^3 - \frac{3}{5}\mathbf{x}, \mathbf{x}^3 - \frac{3}{5}\mathbf{x} \right\rangle \quad \left[\text{Because } \mathbf{w}_4 = \mathbf{x}^3 - \frac{3}{5}\mathbf{x} \right] \\
&= \int_{-1}^1 \left(x^3 - \frac{3}{5}x \right) \left(x^3 - \frac{3}{5}x \right) dx \\
&= \int_{-1}^1 \left(x^6 - \frac{6}{5}x^4 + \frac{9}{25}x^2 \right) dx \\
&= \left[\frac{x^7}{7} - \frac{6x^5}{25} + \frac{3x^3}{25} \right]_{-1}^1 \\
&= \left(\frac{1^7}{7} - \frac{6(1)^5}{25} + \frac{3(1)^3}{25} \right) - \left(\frac{(-1)^7}{7} - \frac{6(-1)^5}{25} + \frac{3(-1)^3}{25} \right) = \frac{8}{175}
\end{aligned}$$

Taking the square root gives $\|\mathbf{w}_4\| = \sqrt{\frac{8}{175}}$. We have

$$\begin{aligned}
\mathbf{w}_3 &= \frac{1}{\|\mathbf{w}_3\|} \mathbf{w}_3 = \frac{1}{\sqrt{8/45}} \left(\mathbf{x}^2 - \frac{1}{3} \right) \quad \left[\text{Because } \|\mathbf{w}_3\| = \sqrt{\frac{8}{45}} \right] \\
&= \sqrt{\frac{45}{8}} \left(\mathbf{x}^2 - \frac{1}{3} \right) \\
&= \sqrt{\frac{9 \times 5}{8}} \left(\frac{3\mathbf{x}^2 - 1}{3} \right) = 3\sqrt{\frac{5}{8}} \left(\frac{3\mathbf{x}^2 - 1}{3} \right) = \sqrt{\frac{5}{8}} (3\mathbf{x}^2 - 1) \\
\mathbf{w}_4 &= \frac{1}{\|\mathbf{w}_4\|} \mathbf{w}_4 = \frac{1}{\sqrt{8/175}} \left(\mathbf{x}^3 - \frac{3}{5}\mathbf{x} \right) \quad \left[\text{Because } \|\mathbf{w}_4\| = \sqrt{\frac{8}{175}} \right] \\
&= \sqrt{\frac{175}{8}} \left(\frac{5\mathbf{x}^3 - 3\mathbf{x}}{5} \right) \\
&= \sqrt{\frac{25 \times 7}{8}} \left(\frac{5\mathbf{x}^3 - 3\mathbf{x}}{5} \right) = 5\sqrt{\frac{7}{8}} \left(\frac{5\mathbf{x}^3 - 3\mathbf{x}}{5} \right) = \sqrt{\frac{7}{8}} (5\mathbf{x}^3 - 3\mathbf{x})
\end{aligned}$$

Collecting our orthonormal basis vectors we have

$$\left\{ \frac{1}{\sqrt{2}}, \sqrt{\frac{3}{2}}\mathbf{x}, \sqrt{\frac{5}{8}}(3\mathbf{x}^2 - 1), \sqrt{\frac{7}{8}}(5\mathbf{x}^3 - 3\mathbf{x}) \right\}$$

Note that the first two vectors are the normalised vectors found in question 12.

19. We need to find an orthonormal basis for the column space $C(\mathbf{A})$ of the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 3 & 3 \\ 2 & 5 & 1 & 0 \\ 0 & 4 & 0 & 0 \end{bmatrix}$$

What is the column space $C(\mathbf{A})$ equal to?

It is the space spanned by the vectors in the columns of the given matrix \mathbf{A} :

$$C(\mathbf{A}) = \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 5 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ 3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix} \right\}$$

You can show that these vectors are linearly independent. *Why do we need to check that these vectors are linearly independent?*

Because we need to convert these vectors into an orthogonal basis which means that we need to use Gram-Schmidt Process (4-10) and this can only be applied if the given vectors are a basis to start of with.

Let $\mathbf{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix}$, $\mathbf{v}_2 = \begin{pmatrix} 0 \\ 1 \\ 5 \\ 4 \end{pmatrix}$, $\mathbf{v}_3 = \begin{pmatrix} 2 \\ 3 \\ 1 \\ 0 \end{pmatrix}$, $\mathbf{v}_4 = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix}$. Applying the Gram-Schmidt Process

(4-10) we have $\mathbf{w}_1 = \mathbf{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix}$. We need to find $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\langle \mathbf{v}_2, \mathbf{w}_1 \rangle = \begin{pmatrix} 0 \\ 1 \\ 5 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix} = 0 + 0 + 10 + 0 = 10$$

$$\|\mathbf{w}_1\|^2 = \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix} = 1^2 + 0^2 + 2^2 + 0^2 = 5$$

Substituting $\mathbf{v}_2 = \begin{pmatrix} 0 \\ 1 \\ 5 \\ 4 \end{pmatrix}$, $\mathbf{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix}$ and $\frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} = \frac{10}{5} = 2$ into $\mathbf{w}_2 = \mathbf{v}_2 - \frac{\langle \mathbf{v}_2, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1$:

$$\mathbf{w}_2 = \begin{pmatrix} 0 \\ 1 \\ 5 \\ 4 \end{pmatrix} - 2 \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 0-2 \\ 1-0 \\ 5-4 \\ 4-0 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 1 \\ 4 \end{pmatrix}$$

Next we find $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$:

$$\langle \mathbf{v}_3, \mathbf{w}_1 \rangle = \begin{pmatrix} 2 \\ 3 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix} = 2 + 0 + 2 + 0 = 4$$

$$\langle \mathbf{v}_3, \mathbf{w}_2 \rangle = \begin{pmatrix} 2 \\ 3 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -2 \\ 1 \\ 1 \\ 4 \end{pmatrix} = -4 + 3 + 1 + 0 = 0$$

This means that \mathbf{v}_3 and \mathbf{w}_2 are orthogonal. Substituting $\mathbf{v}_3 = \begin{pmatrix} 2 \\ 3 \\ 1 \\ 0 \end{pmatrix}$, $\mathbf{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix}$,

$\frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} = \frac{4}{5}$, and $\langle \mathbf{v}_3, \mathbf{w}_2 \rangle = 0$ into $\mathbf{w}_3 = \mathbf{v}_3 - \frac{\langle \mathbf{v}_3, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_3, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2$ gives

$$\mathbf{w}_3 = \begin{pmatrix} 2 \\ 3 \\ 1 \\ 0 \end{pmatrix} - \frac{4}{5} \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix} - 0 \mathbf{w}_2 = \begin{pmatrix} 2-4/5 \\ 3-0 \\ 1-8/5 \\ 0-0 \end{pmatrix} = \begin{pmatrix} 6/5 \\ 3 \\ -3/5 \\ 0 \end{pmatrix} = \frac{3}{5} \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix}$$

Ignore the fraction and let $\mathbf{w}'_3 = \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix}$. What else do we need to find?

\mathbf{w}_4 where $\mathbf{w}_4 = \mathbf{v}_4 - \frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2 - \frac{\langle \mathbf{v}_4, \mathbf{w}'_3 \rangle}{\|\mathbf{w}'_3\|^2} \mathbf{w}'_3$. We have

$$\langle \mathbf{v}_4, \mathbf{w}_1 \rangle = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix} = 1 + 0 + 0 + 0 = 1$$

$$\langle \mathbf{v}_4, \mathbf{w}_2 \rangle = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -2 \\ 1 \\ 1 \\ 4 \end{pmatrix} = -2 + 3 + 0 + 0 = 1$$

$$\langle \mathbf{v}_4, \mathbf{w}'_3 \rangle = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix} = 2 + 15 + 0 + 0 = 17$$

$$\|\mathbf{w}_2\|^2 = \begin{pmatrix} -2 \\ 1 \\ 1 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} -2 \\ 1 \\ 1 \\ 4 \end{pmatrix} = 4 + 1 + 1 + 16 = 22$$

$$\|\mathbf{w}'_3\|^2 = \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix} = 4 + 25 + 1 + 0 = 30$$

Substituting $\mathbf{v}_4 = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix}$, $\mathbf{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix}$, $\mathbf{w}_2 = \begin{pmatrix} -2 \\ 1 \\ 1 \\ 4 \end{pmatrix}$, $\mathbf{w}'_3 = \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix}$, $\frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} = \frac{1}{5}$,

$\frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} = \frac{1}{22}$ and $\frac{\langle \mathbf{v}_4, \mathbf{w}'_3 \rangle}{\|\mathbf{w}'_3\|^2} = \frac{17}{30}$ into

$$\mathbf{w}_4 = \mathbf{v}_4 - \frac{\langle \mathbf{v}_4, \mathbf{w}_1 \rangle}{\|\mathbf{w}_1\|^2} \mathbf{w}_1 - \frac{\langle \mathbf{v}_4, \mathbf{w}_2 \rangle}{\|\mathbf{w}_2\|^2} \mathbf{w}_2 - \frac{\langle \mathbf{v}_4, \mathbf{w}'_3 \rangle}{\|\mathbf{w}'_3\|^2} \mathbf{w}'_3$$

we have

$$\begin{aligned} \mathbf{w}_4 &= \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix} - \frac{1}{5} \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix} - \frac{1}{22} \begin{pmatrix} -2 \\ 1 \\ 1 \\ 4 \end{pmatrix} - \frac{17}{30} \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} 1 - 1/5 + 2/22 - 34/30 \\ 3 - 0 - 1/22 - 85/30 \\ 0 - 2/5 - 1/22 + 17/30 \\ 0 - 0 - 4/22 - 0 \end{pmatrix} \\ &= \begin{pmatrix} -8/33 \\ 4/33 \\ 4/33 \\ -4/22 \end{pmatrix} = \begin{pmatrix} -16/66 \\ 8/66 \\ 8/66 \\ -12/66 \end{pmatrix} = \frac{4}{66} \begin{pmatrix} -4 \\ 2 \\ 2 \\ -3 \end{pmatrix} \end{aligned}$$

Again ignoring the fraction and let $\mathbf{w}'_4 = \begin{pmatrix} -4 \\ 2 \\ 2 \\ -3 \end{pmatrix}$. Our orthogonal basis is

$$\left\{ \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 1 \\ 1 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ 5 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} -4 \\ 2 \\ 2 \\ -3 \end{pmatrix} \right\}$$

20. Need to prove that if \mathbf{u} is orthogonal for every $\mathbf{v} \in V$ then $\mathbf{u} = \mathbf{0}$.

Proof.

Since we are given that the vector \mathbf{u} is orthogonal for every $\mathbf{v} \in V$ therefore

$$\langle \mathbf{u}, \mathbf{v} \rangle = 0 \text{ for every } \mathbf{v} \in V$$

Let $\mathbf{u} = \mathbf{v}$ then by the above we have $\langle \mathbf{u}, \mathbf{v} \rangle = \langle \mathbf{u}, \mathbf{u} \rangle = 0$. By Definition (4-1) part (d) we have $\langle \mathbf{u}, \mathbf{u} \rangle = 0 \Leftrightarrow \mathbf{u} = \mathbf{O}$. This completes our proof. ■

21. We need to prove that if \mathbf{u} is orthogonal to \mathbf{v} then every scalar multiple of \mathbf{u} is also orthogonal to \mathbf{v} .

Proof.

We are given that $\langle \mathbf{u}, \mathbf{v} \rangle = 0$ because \mathbf{u} and \mathbf{v} are orthogonal. Consider $\langle k\mathbf{u}, \mathbf{v} \rangle = 0$ where k is any scalar. We have

$$\langle k\mathbf{u}, \mathbf{v} \rangle = k \langle \mathbf{u}, \mathbf{v} \rangle = k(0) = 0$$

Thus $k\mathbf{u}$ and \mathbf{v} are orthogonal which means every scalar multiple of \mathbf{u} is orthogonal to \mathbf{v} . ■

22. We need to prove

$$\langle x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + \cdots + x_n\mathbf{v}_n, y_1\mathbf{v}_1 + y_2\mathbf{v}_2 + \cdots + y_n\mathbf{v}_n \rangle = x_1y_1 + x_2y_2 + \cdots + x_ny_n$$

Proof.

We are given that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ is a set of orthonormal vectors. This means that $\langle \mathbf{v}_i, \mathbf{v}_j \rangle = 0$ ($i \neq j$) and $\|\mathbf{v}_i\| = 1$ for $i = 1, 2, \dots, n$. Applying this we have

$$\begin{aligned} \langle x_1\mathbf{v}_1 + \cdots + x_n\mathbf{v}_n, y_1\mathbf{v}_1 + \cdots + y_n\mathbf{v}_n \rangle &= x_1y_1 \langle \mathbf{v}_1, \mathbf{v}_1 \rangle + \cdots + x_ny_n \langle \mathbf{v}_n, \mathbf{v}_n \rangle \\ &= x_1y_1 \|\mathbf{v}_1\|^2 + \cdots + x_ny_n \|\mathbf{v}_n\|^2 \\ &= x_1y_1 + \cdots + x_ny_n \end{aligned}$$

Thus we have our required result. ■

23. Need to prove that if $\mathbf{u} \neq \mathbf{v}$ then $d(\mathbf{u}, \mathbf{v}) > 0$.

Proof.

By using the definition of distance function we have

$$d(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\|$$

By the properties of norm given in Proposition (4-2) part (a) which says:

$$\|\mathbf{u}\| \geq 0 \text{ [Non-negative]}$$

We have $d(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\| \geq 0$. Since we are given that $\mathbf{u} \neq \mathbf{v}$ which implies $\mathbf{u} - \mathbf{v} \neq \mathbf{O}$ [Not Zero] therefore by the same proposition part (ii) which says:

$$\|\mathbf{u}\| = 0 \Leftrightarrow \mathbf{u} = \mathbf{O}$$

We must have $d(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\| > 0$ which is our required result. ■

(b) We need to prove $d(\mathbf{u}, \mathbf{v}) \leq d(\mathbf{u}, \mathbf{w}) + d(\mathbf{w}, \mathbf{v})$.

How do we prove this result?

By using Minkowski's Inequality (4-4) which says

$$\|\mathbf{u} + \mathbf{v}\| \leq \|\mathbf{u}\| + \|\mathbf{v}\|$$

Proof.

We have $d(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\|$. By rewriting this

$$\|\mathbf{u} - \mathbf{v}\| = \|\mathbf{u} - \mathbf{w} + \mathbf{w} - \mathbf{v}\|$$

Applying Minkowski's Inequality (4-4) to this we have

$$\|\mathbf{u} - \mathbf{v}\| = \|(\mathbf{u} - \mathbf{w}) + (\mathbf{w} - \mathbf{v})\|$$

$$\leq \|\mathbf{u} - \mathbf{w}\| + \|\mathbf{w} - \mathbf{v}\|$$

$$= d(\mathbf{u}, \mathbf{w}) + d(\mathbf{w}, \mathbf{v})$$

Hence we have our result $d(\mathbf{u}, \mathbf{v}) \leq d(\mathbf{u}, \mathbf{w}) + d(\mathbf{w}, \mathbf{v})$.

■